

BFS

Breadth First Search

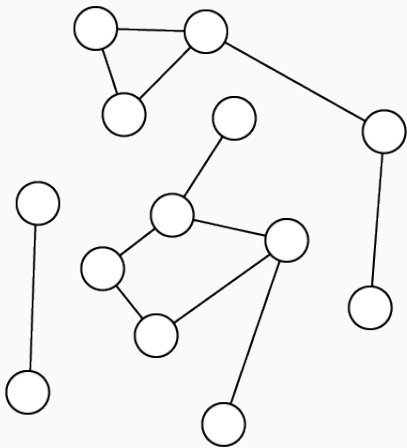
Daniel Graf (Slides by Benjamin Schmid)

2017-11-04

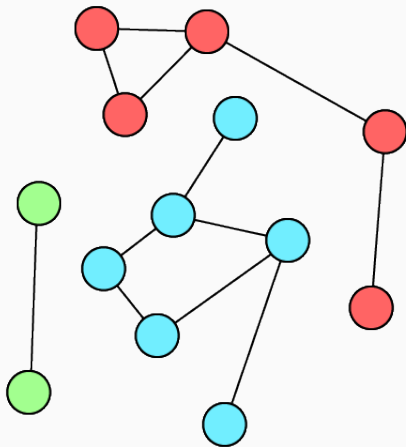
Swiss Olympiad in Informatics

Introduction

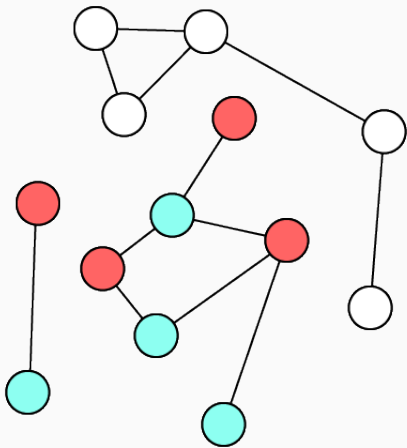
Graph traversal



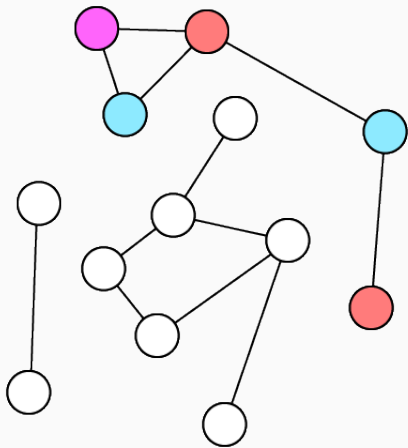
Components



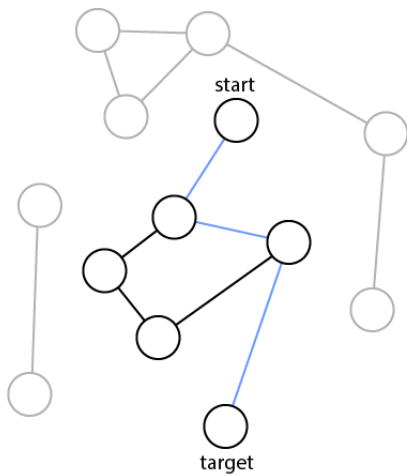
Bipartite



Bipartite

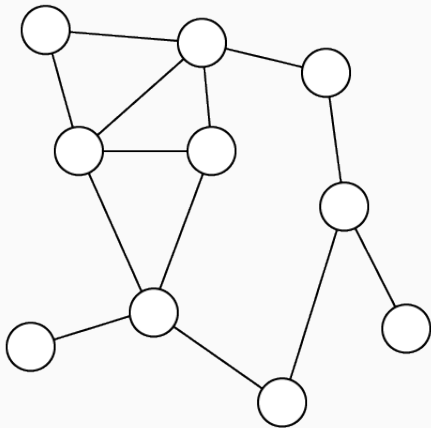


Shortest path

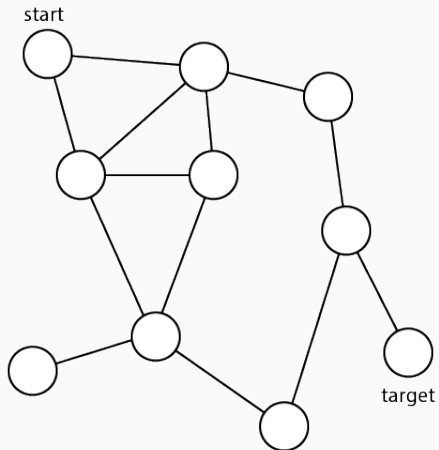


Shortest path

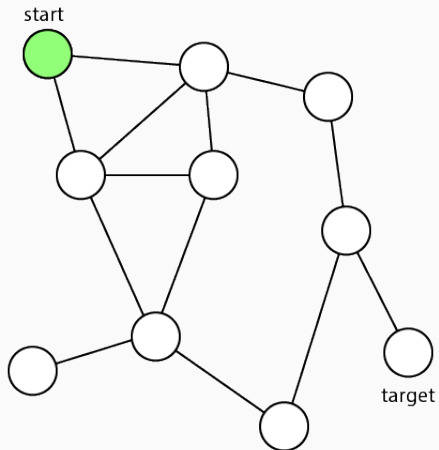
Shortest path



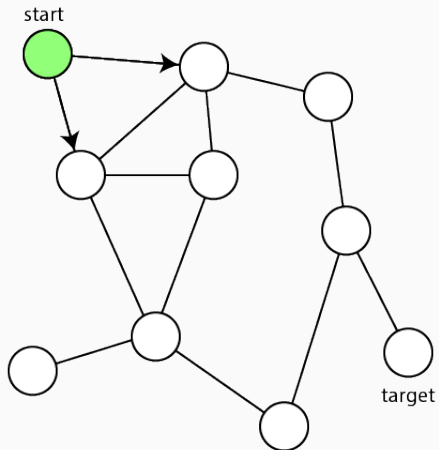
Shortest path



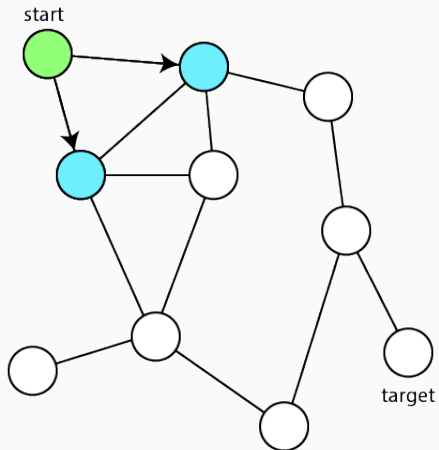
Shortest path



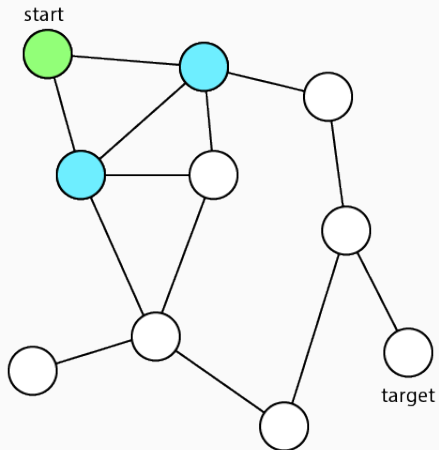
Shortest path



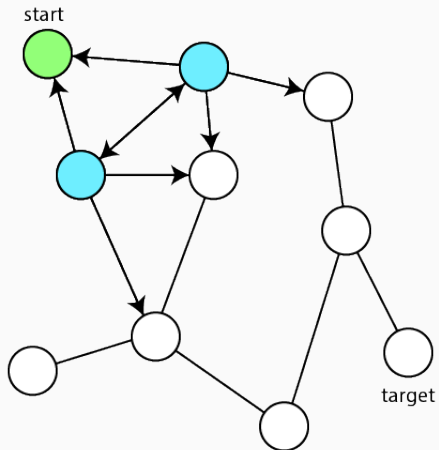
Shortest path



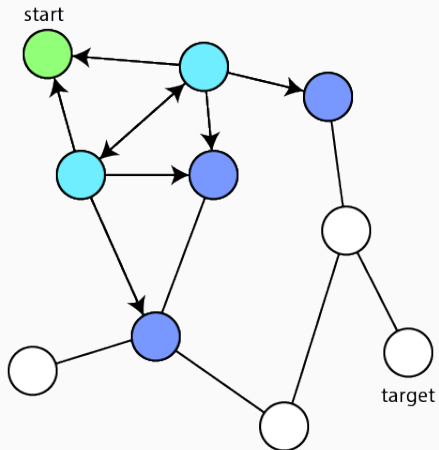
Shortest path



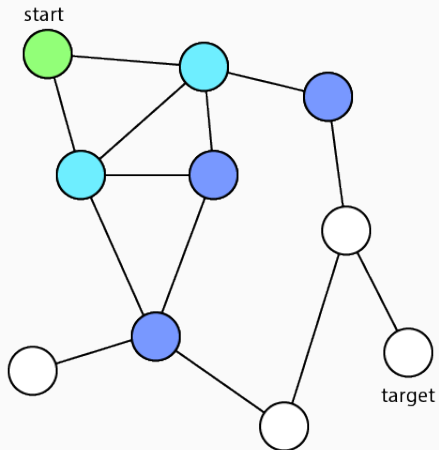
Shortest path



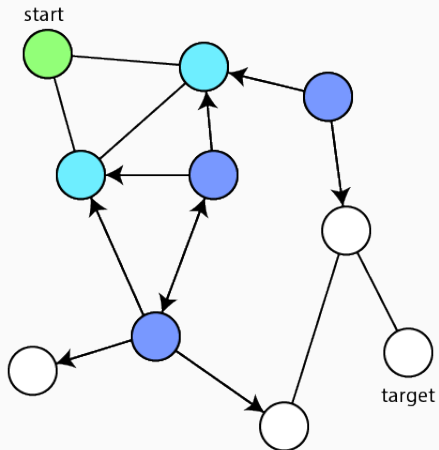
Shortest path



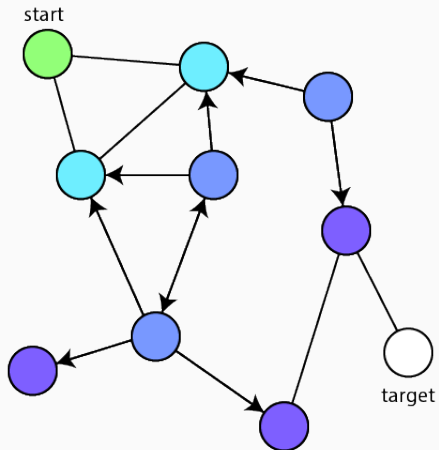
Shortest path



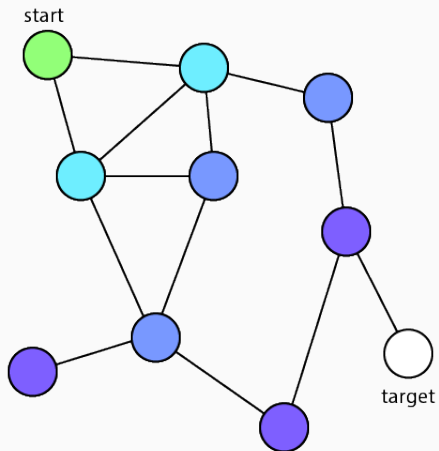
Shortest path



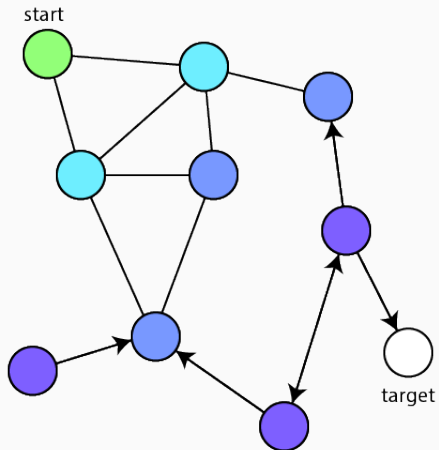
Shortest path



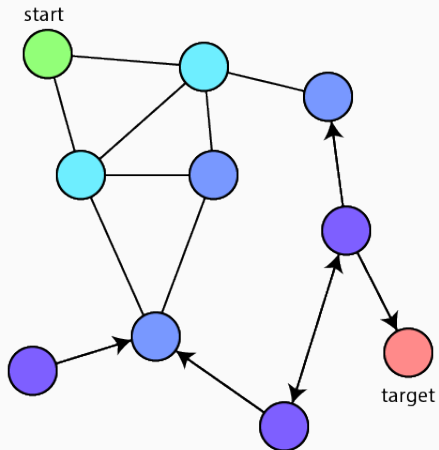
Shortest path



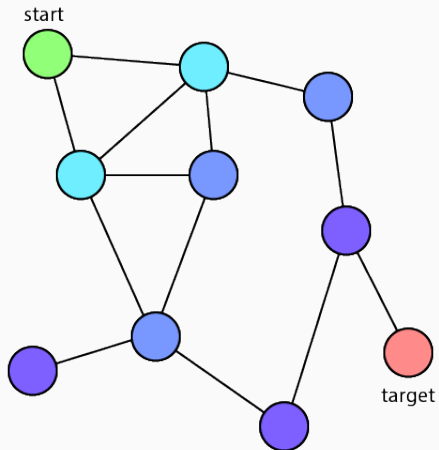
Shortest path



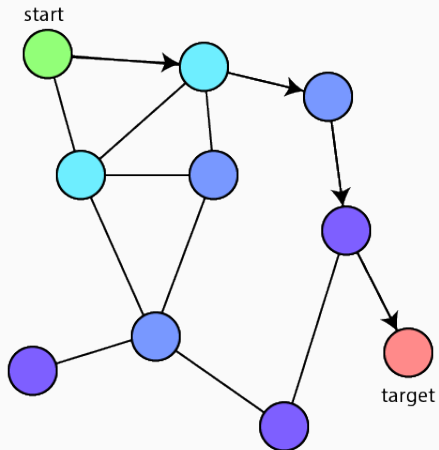
Shortest path



Shortest path



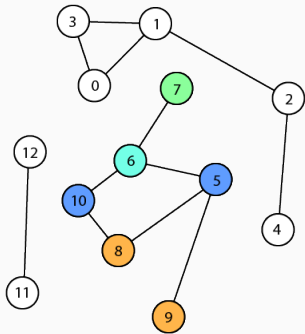
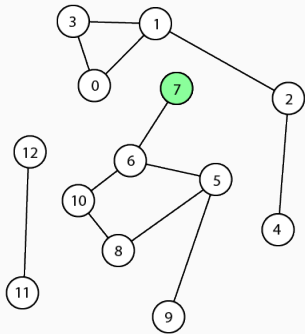
Shortest path



- Breadth First Search (BFS)
- First explore breadth
- Nodes visited in order of distance to start
- Thus find shortest path (if equal lengths)

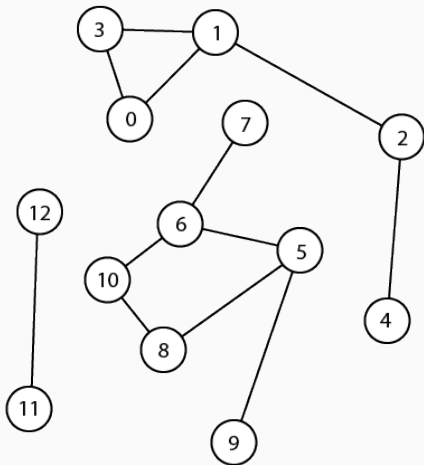
BFS Implementation

Find Component



Generations / Queue

Generations:
[]

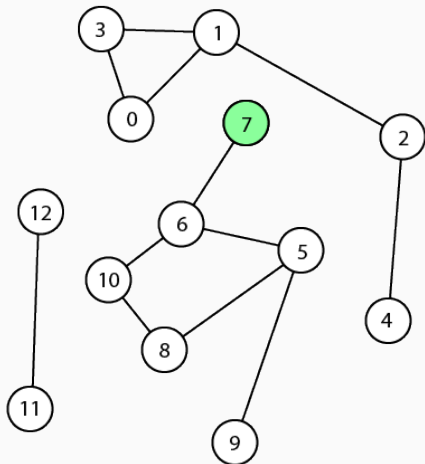


Generations / Queue

Generations:

[7]

[]

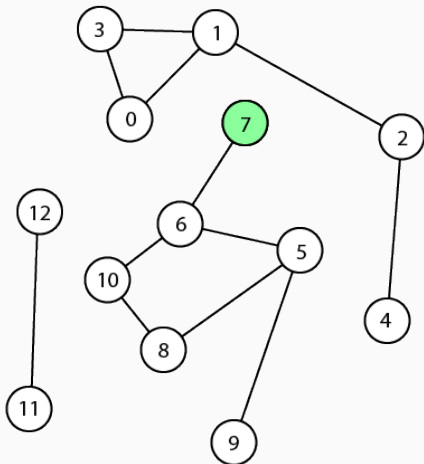


Generations / Queue

Generations:

[7]

[6]

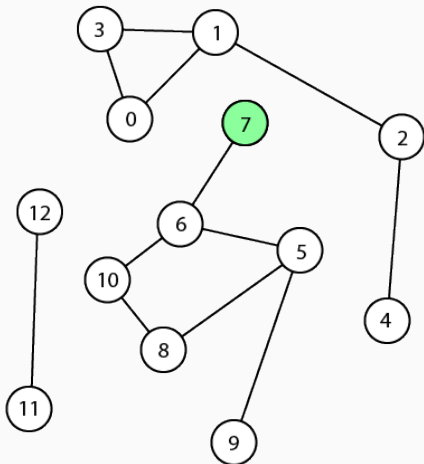


Generations / Queue

Generations:

[7]

[6]



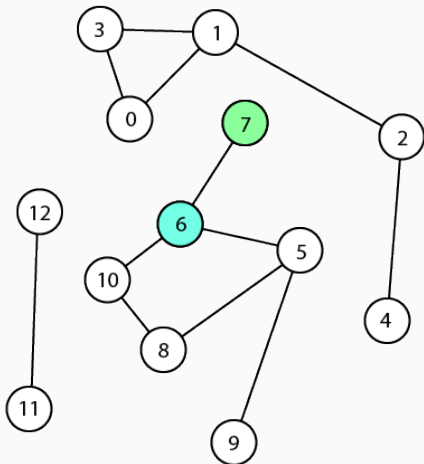
Generations / Queue

Generations:

[7]

[6]

[]



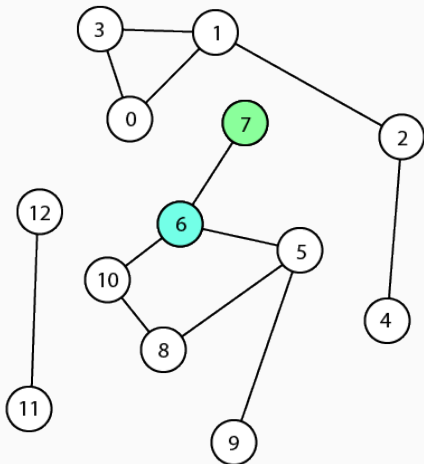
Generations / Queue

Generations:

[7]

[6]

[10, 5]



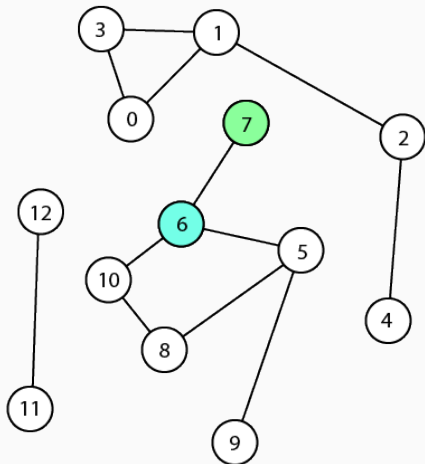
Generations / Queue

Generations:

[7]

[6]

[10, 5]



Generations / Queue

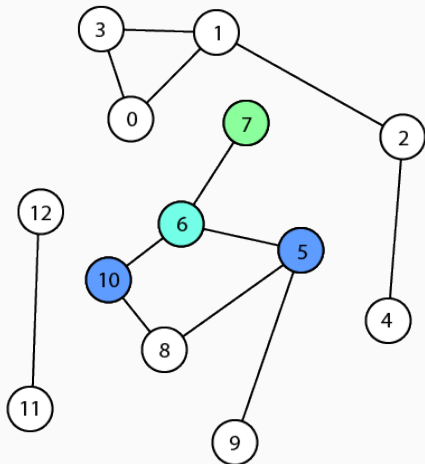
Generations:

[7]

[6]

[10, 5]

[]



Generations / Queue

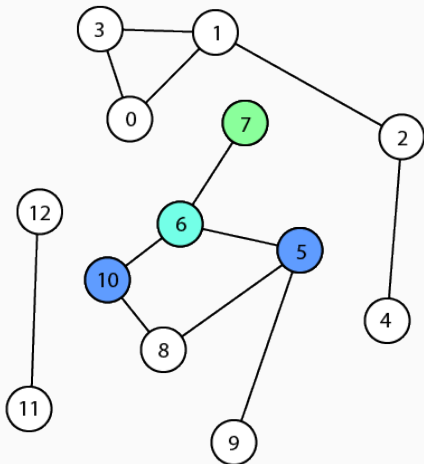
Generations:

[7]

[6]

[10, 5]

[8]



Generations / Queue

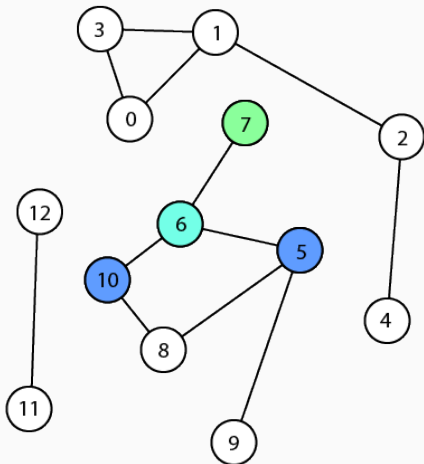
Generations:

[7]

[6]

[10, 5]

[8]



Generations / Queue

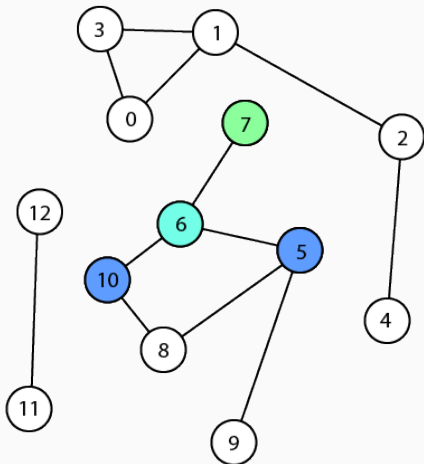
Generations:

[7]

[6]

[10, 5]

[8]



Generations / Queue

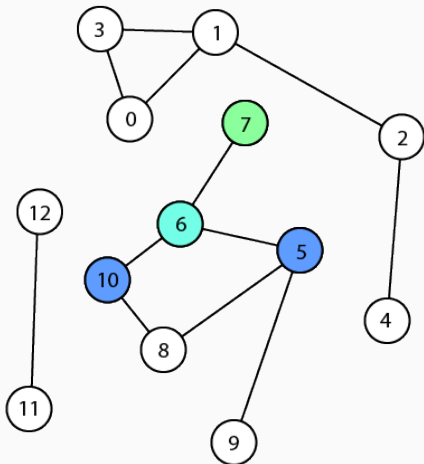
Generations:

[7]

[6]

[10, 5]

[8, 9]

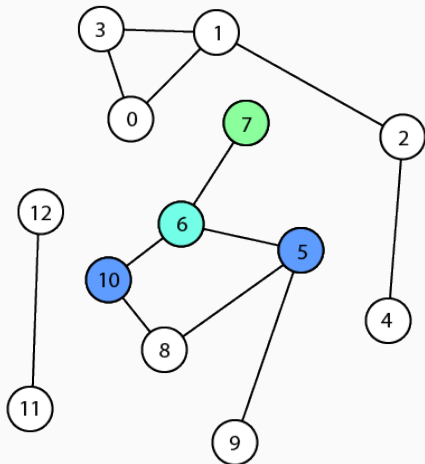


Generations / Queue

Generations:

[7]

[6]

 $[10, 5]$ $[8, 9]$ 

Generations:

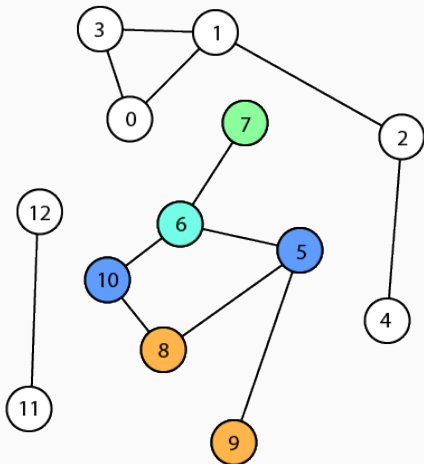
[7]

[6]

[10, 5]

[8, 9]

[]



Generations / Queue

Generations:

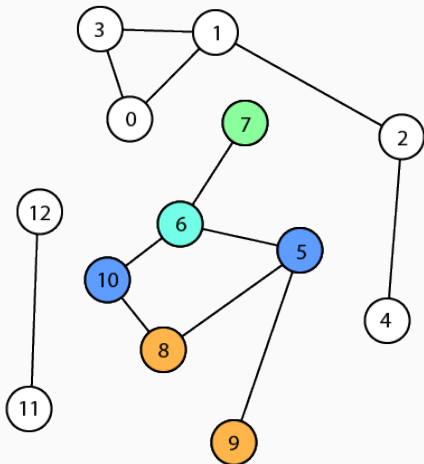
[7]

[6]

[10, 5]

[8, 9]

[]



Generations:

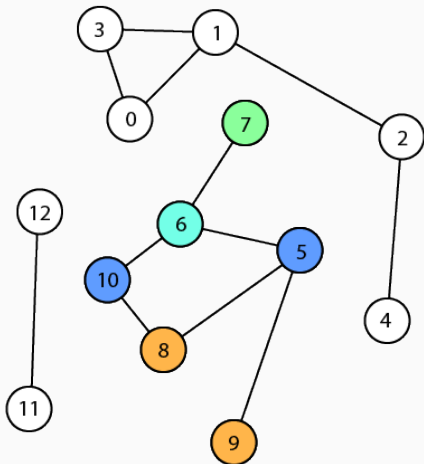
[7]

[6]

[10, 5]

[8, 9]

[]



Generations / Queue

Generations:

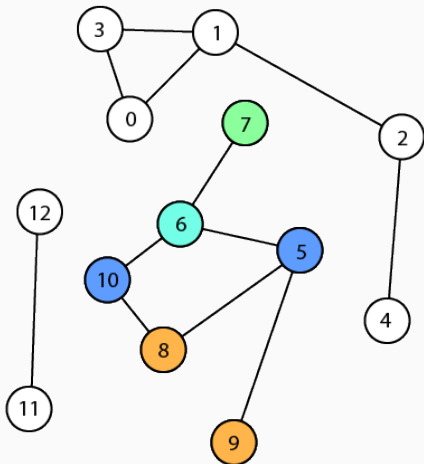
[7]

[6]

[10, 5]

[8, 9]

[]



Generations

[7]

[6]

[10, 5]

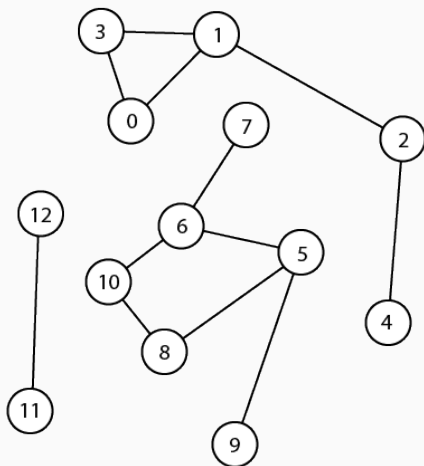
[8, 9]

Queue (first in, first out)

[7, 6, 10, 5, 8, 9]

Adjacency List

0: [1, 3]
1: [0, 2, 3]
2: [1, 4]
3: [0, 1]
4: [2]
5: [6, 8, 9]
6: [5, 7, 10]
7: [6]
8: [5, 10]
9: [5]
10: [6, 8]
11: [12]
12: [11]



BFS Implementation

- Visited flag for each node
- Queue to store neighbors
- graph is adjacency list

```
1  from collections import deque
2
3  def bfs(start):
4      q = deque()
5      visited = [False] * len(graph)
```

BFS Implementation

- Process start node

```
1  def bfs(start):  
2      ...  
3      visited[start] = True  
4      q.appendleft(start)
```


BFS Implementation

- Process neighbors
- Check whether not visited
- Add to queue and set visited

```
1  def bfs(start):  
2      ...  
3      while len(q) > 0:  
4          current = q.pop()  
5          for neighbor in graph[current]:  
6              if not visited[neighbor]:  
7                  q.appendleft(neighbor)  
8                  visited[neighbor] = True
```

BFS Implementation

- Return visited nodes

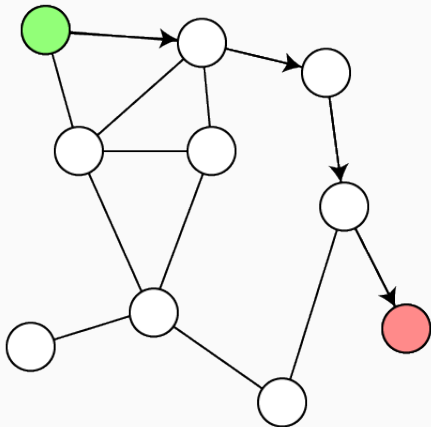
```
1  def bfs(start , end):  
2      ...  
3      return visited
```

BFS Implementation

```
1  def bfs(start):
2      q = deque() # initialize
3      visited = [False] * len(graph)
4
5      visited[start] = True
6      q.appendleft(start)
7
8      while len(q) > 0: # traverse graph
9          current = q.pop()
10         for neighbor in graph[current]:
11             if not visited[neighbor]:
12                 q.appendleft(neighbor)
13                 visited[neighbor] = True
14     return visited
```

Shortest Distance Implementation

Shortest Distance



Shortest Distance Implementation

1. List of distance to start
2. Upon adding to queue, store distance

Shortest Distance Implementation

- List of distance to start

```
1  def bfs(start , target):  
2      ...  
3      visited = [False] * len(graph)  
4      distance = [0] * len(graph)  
5      ...
```

Shortest Distance Implementation

- Store distance

```
1  def bfs(start , target):  
2      ...  
3      visited[neighbor] = True  
4      distance[neighbor] = distance[current] + 1  
5      ...
```


Shortest Distance Implementation

- Return shortest distance
- Note: we know shortest distance to every node

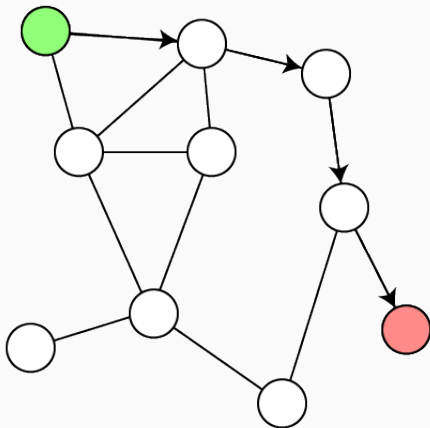
```
1  def bfs(start , target):  
2      ...  
3      return distance[target]
```

Shortest Distance Implementation

```
1  def bfs(start, target):
2      q = deque() # initialize
3      visited = [False] * len(graph)
4      distance = [0] * len(graph)
5
6      visited[start] = True
7      q.appendleft(start)
8
9      while len(q) > 0: # traverse graph
10         current = q.pop()
11         for neighbor in graph[current]:
12             if not visited[neighbor]:
13                 q.appendleft(neighbor)
14                 visited[neighbor] = True
15                 distance[neighbor] = distance[current] + 1
16     return distance[target]
```

Shortest Path Implementation

Shortest Path



Shortest Path Implementation

1. Store "parent" of node
2. Upon adding to queue, store parent

Shortest Path Implementation

- List of parents

```
1  def bfs(start , target):  
2      ...  
3      visited = [False] * len(graph)  
4      parent = [-1] * len(graph)  
5      ...
```

Shortest Path Implementation

- Store parent

```
1  def bfs(start , target):  
2      ...  
3      visited[neighbor] = True  
4      parent[neighbor] = current  
5      ...
```

Shortest Path Implementation

- Return shortest path
- Note: we know shortest path to every node

```
1  def bfs(start , target):  
2      ...  
3      if parent[target] == -1:  
4          return []  
5      path = []  
6      current = target  
7      while current != -1:  
8          path.append(current)  
9          current = parent[current]  
10     return reversed(path)
```


Shortest Path Implementation

```
1 def bfs(start, target):
2     q = deque() # initialize
3     visited = [False] * len(graph)
4     parent = [-1] * len(graph)
5
6     visited[start] = True
7     q.appendleft(start)
8
9     while len(q) > 0: # traverse graph
10         current = q.pop()
11         for neighbor in graph[current]:
12             if not visited[neighbor]:
13                 q.appendleft(neighbor)
14                 visited[neighbor] = True
15                 parent[neighbor] = current
16
17     if parent[target] == -1: # reconstruct path
18         return []
19     path = []
20     current = target
21     while current != -1:
22         path.append(current)
23         current = parent[current]
24     return list(reversed(path))
```

Runtime

- Each node is visited exactly once
- Each edge is visited exactly twice

$$\mathcal{O}(n + m)$$

Summary

- Works with directed graphs
- Can find shortest path to all nodes
- Sometimes only implicit state

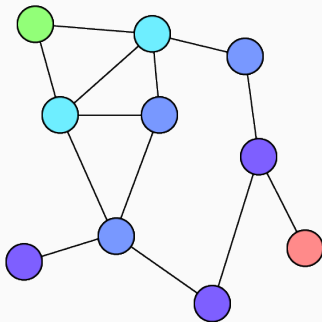


Summary

- Similar to DFS
- Progress "by generation"
- Useful for many different problems
- E.g. components, shortest path, bipartite

Conclusion

Bug Bounty: 1 Prügeli
(expires Sunday 10pm)



And now is your last chance for Pizza!