

# **DP 3: All-pairs Shortest Paths**

Johannes Kapfhammer

11 November 2019



Weighted graph V, E with |V| = NWeights correspond to lengths  $\geq$  0. What is the shortest path from u to v? (for all  $u, v \in V$ )

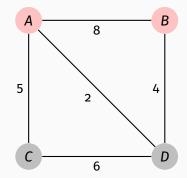


#### Adjacency Matrix

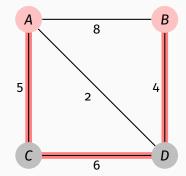
G[i][j] : length of edge from *i* to *j*.  $G[i][j] = \infty$  : no edge from *i* to *j*. G[i][i] = 0

The edge weights should be non-negative, since cycles of negative length are problematic.

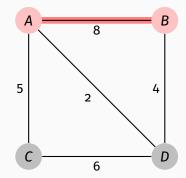




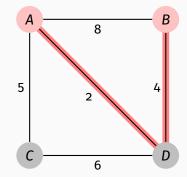




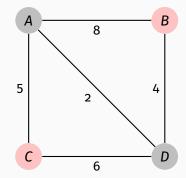




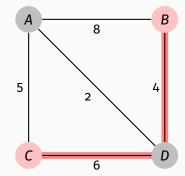












### Important properties of shortest paths



A shortest path doesn't contain cycles.

### Important properties of shortest paths



### A shortest path doesn't contain cycles. Every subpath of a shortest path is also a shortest path.



#### DP[i][j] : length of a shortest path from *i* to *j*.

#### **Optimal substructure** If *k* is located on the shortest path:

 $\mathrm{DP}[i][j] = \mathrm{DP}[i][k] + \mathrm{DP}[k][i]$ 



#### DP[i][j] : length of a shortest path from *i* to *j*.

#### **Optimal substructure** If *k* is located on the shortest path:

$$DP[i][j] = DP[i][k] + DP[k][i]$$

# Computation? $DP[i][j] = \min\left(G[i][j], \min_{k \in V} (DP[i][k] + DP[k][j])\right)$



Computation?  

$$DP[i][j] = \min\left(G[i][j], \min_{k \in V} (DP[i][k] + DP[k][j])\right)$$



Computation?  

$$DP[i][j] = \min \left( G[i][j], \min_{k \in V} (DP[i][k] + DP[k][j]) \right)$$

#### **Cyclic dependencies**

$$\mathrm{DP}[\mathbf{1}][\mathbf{2}] \Leftarrow \mathrm{DP}[\mathbf{1}][\mathbf{3}] \Leftarrow \mathrm{DP}[\mathbf{1}][\mathbf{2}] \Leftarrow \dots$$

DP state is too small!



# DP[l][i][j]: length of a shortest path from *i* to *j* using at most *l* edges.



DP[*l*][*i*][*j*] : length of a shortest path from *i* to *j* using at most *l* edges.

#### **Optimal substructure**

The first l - 1 edges of a shortest path are also a shortest path.

$$DP[l][i][j] = \min_{k \in V} (DP[l - 1][i][k] + G[k][j])$$
$$DP[1][i][j] = G[i][j]$$

 $\Rightarrow$  no more cyclic dependencies.



# DP[l][i][j]: length of a shortest path from *i* to *j* using at most *l* edges.

$$\mathrm{DP}[l][i][j] = \min_{k \in V} \left( \mathrm{DP}[l-1][i][k] + G[k][j] \right)$$



# DP[l][j][j] : length of a shortest path from *i* to *j* using at most *l* edges.

$$DP[l][i][j] = \min_{k \in V} (DP[l-1][i][k] + G[k][j])$$

 $\Theta(N^3)$  states, each requiring  $\Theta(N)$  time.  $\Theta(N^4)$  running time and  $\Theta(N^3)$  memory.

# Repaired DP approach – top-down



```
vector<vector<vector<int>>> cache(n.
1
     \rightarrow vector<vector<int>>(n, vector<int>(n, -1)));
    const int INF = 1e9:
2
    int dp(int 1, int i, int j) {
3
        if (1 == 0) return G[i][j];
4
        int &c = cache[1][i][j];
5
        if (c != -1) return c:
6
        c = INF;
7
        for (int k = 0; k < n; ++k) {
8
             c = min(c, dp(1-1, i, k) + G[k][j]);
9
        }
10
        return c;
11
    }
12
```



# DP[k][i][j]: length of a shortest path from *i* to *j* through vertices with index < k.



DP[k][i][j]: length of a shortest path from *i* to *j* through vertices with index < k.

**Optimal substructure** The shortest path either goes through vertex *k*, or it avoids *k*.

$$\begin{split} \mathrm{DP}[k+1][i][j] &= \min\left(\mathrm{DP}[k][i][k] + \mathrm{DP}[k][k][j], \mathrm{DP}[k][i][j]\right) \\ \mathrm{DP}[\mathbf{0}][i][j] &= G[i][j] \end{split}$$

## Improved DP approach – top-down



```
vector<vector<vector<int>>> cache(n.
1
    \rightarrow vector<vector<int>>(n, vector<int>(n, -1)));
    int dp(int k, int i, int j) {
2
        if (k == 0) return G[k][i][j];
3
        if (cache[k][i][j] != -1) return cache[k][i][j];
4
        cache[k][i][j] = min(
5
            dp(k-1, i, k-1) + dp(k-1, k-1, j),
6
            dp(k-1, i, j)
7
        );
8
        return cache[k][i][j];
9
    }
10
```



```
vector<vector<vector<int>>> cache(n.
1
    \rightarrow vector<vector<int>>(n, vector<int>(n, -1)));
    int dp(int k, int i, int j) {
2
        if (k == 0) return G[k][i][j];
3
        if (cache[k][i][j] != -1) return cache[k][i][j];
4
        cache[k][i][j] = min(
5
            dp(k-1, i, k-1) + dp(k-1, k-1, j),
6
            dp(k-1, i, j)
7
        );
8
        return cache[k][i][j];
9
    }
10
```

 $\Theta(N^3)$  states, each requiring  $\Theta(1)$  time.  $\Theta(N^3)$  running time and memory.

## Improved DP approach – bottom up



```
vector<vector<int>>> DP(n,
1
    → vector<vector<int>>(n, vector<int>(n, INF)));
   for (int i=0:i < n:++i)
2
     for (int j=0;j<n;++j)</pre>
3
       DP[0][i][j] = G[i][j];
4
   for (int k = 0; k < n; ++k)
5
     for (int i = 0; i < n; ++i)
6
       for (int j = 0; j < n; ++j)
7
         DP[k+1][i][j] = min(DP[k][i][k] + DP[k][k][j],
8
                              DP[k][i][j]);
9
```

 $\Theta(N^3)$  states, each requiring  $\Theta(1)$  time.  $\Theta(N^3)$  running time and memory.



1	<pre>vector<vector<int>&gt; DP = G;</vector<int></pre>
2	for (int $k = 0$ ; $k < n$ ; ++k) // k is outermost
3	
4	for (int j = 0; j < n; ++j)
5	DP[i][j] = min(DP[i][k] + DP[k][j], DP[i][j]);

 $\Theta(N^3)$  running time,  $\Theta(N^2)$  memory.



#### Everything that needs shortest paths

- Diameter of a graph.
- Possibly some task of the first round



#### Everything that needs shortest paths

- Diameter of a graph.
- Possibly some task of the first round

The algorithm also works on weighted graphs with negative weights.